## Load Cell and Torque Sensor - X/Y/Z

Configurable up to $3 x$ force $/ 3 x$ torque

## MODEL 8565 NEw

## Preliminary data sheet




Strain gage output


Robot flange in accordance with DIN ISO 9049-1


Direction of action

## Highlights

- 6-axis sensor

■ Measuring range Fx: $1 \mathrm{kN} / \mathrm{Fy}: 1 \mathrm{kN} / \mathrm{Fz}_{\mathrm{z}} 2 \mathrm{kN}$
$\mathrm{Mx}: 50 \mathrm{Nm} / \mathrm{My}: 50 \mathrm{Nm} / \mathrm{Mz}: 50 \mathrm{Nm}$

- Other measuring ranges available on request
- Non-linearity < 0.1 \% F.S.
- Excellent price/performance ratio
- Customer-specific axis configuration


## Applications

- Robot-assisted applications
- Pick \& place
- Tactile sensing in manufacturing
- Collision detection
- Force-controlled machining


## Product description

In robotics and automation engineering, the requirements for precise, tactile handling are constantly increasing. The robust 8565 multi-axis sensor with its low crosstalk enables you to monitor and evaluate your process at any time, regardless of the sensor's orientation.

With just one sensor, you can obtain accurate three-dimensional load information. Its six independent outputs let you selectively evaluate the direction of action of the loads (axial force [Fz] / lateral forces [Fx/Fy] / torque $[M z]$ / bending moment $[M x / M y]$ ).

Thanks to its compact design and adaptation via the standardized robot flange in accordance with DIN ISO 9049-1, the sensor can be integrated into many applications quickly and easily.

When the slightest deviations are detected in your fast-moving and complex production processes, you can intervene immediately to make adjustments. This helps to prevent faulty parts and reduce manufacturing costs.

## Technical data

| 8565 | - | 60025050 |
| :---: | :---: | :---: |
| Measuring range Fx calibrated in N from O |  | $\mathrm{Fx}_{\mathrm{x}}=0 \ldots \pm 1 \mathrm{kN}(0 \ldots \pm 224.8 \mathrm{lbs})$ |
| Measuring range Fy calibrated in N from O . |  | Fy $=0 \ldots \pm 1 \mathrm{kN}(0 \ldots \pm 224.8 \mathrm{lbs})$ |
| Measuring range Fz calibrated in N from O |  | $\mathrm{Fz}=0 \ldots \pm 2 \mathrm{kN}(0 \ldots \pm 449.6 \mathrm{lbs})$ |
| Measuring range Mx calibrated in Nm from 0 . |  | $M x=0 \ldots \pm 50 \mathrm{Nm}(0 \ldots \pm 442.51 \mathrm{lbs}$ in) |
| Measuring range My calibrated in Nm from O |  | My $=0 \ldots \pm 50 \mathrm{Nm}(0 \ldots \pm 442.51 \mathrm{lbs}$ in) |
| Measuring range Mz calibrated in Nm from O |  | $\mathrm{Mz}=0 \ldots \pm 50 \mathrm{Nm}(0 \ldots \pm 442.51 \mathrm{lbs}$ in) |
| Accuracy |  |  |
| Relative non-linearity * |  | $< \pm 0.1$ \% F.S. |
| Relative hysteresis |  | 0.2 \% F.S. |
| Characteristic curve deviation* |  | < $\pm 0.15$ \% F.S. |
| Crosstalk |  | $<5 \%$ from Fz to other axes (other crosstalk significantly less) |
| Temperature effect on zero output |  | $\leq \pm 0.02$ \% F.S./K |
| Temperature effect on nominal sensitivity |  | $\leq \pm 0.02$ \% F.S./K |
| Electrical values |  |  |
| Sensitivity (nominal) Fx: |  | $1.2 \mathrm{mV} / \mathrm{V}$ |
| Sensitivity (nominal) Fy: |  | $1.2 \mathrm{mV} / \mathrm{V}$ |
| Sensitivity (nominal) Fz: |  | $0.4 \mathrm{mV} / \mathrm{V}$ |
| Sensitivity (nominal) Mx: |  | $1 \mathrm{mV} / \mathrm{V}$ |
| Sensitivity (nominal) My: |  | $1 \mathrm{mV} / \mathrm{V}$ |
| Sensitivity (nominal) Mz: |  | $0.9 \mathrm{mV} / \mathrm{V}$ |
| Measurement direction |  | Positive output signal for compressive load / torque in the direction of the marked $\mathrm{X}, \mathrm{Y}$ or Z axis |
| Bridge resistance |  | $350 \Omega / 700 \Omega$ nominal (deviations are possible) |
| Excitation voltage |  | 5 V DC (max. 10 V DC) |
| Environmental condifions |  |  |
| Nominal temperature range |  | $+15^{\circ} \mathrm{C} \ldots+70^{\circ} \mathrm{C}$ |
| Operating temperature range |  | $-10^{\circ} \mathrm{C} \ldots+80^{\circ} \mathrm{C}$ |
| Mechanical values |  |  |
| Deflection full scale |  | Fx and $\mathrm{Fy}<0.04 \mathrm{~mm} / \mathrm{Fz}<0.015 \mathrm{~mm}$ |
| Max. operational force (Dynamic load limit 250) |  | $L \max =100 * \frac{\sqrt{F x^{2}+F y^{2}}}{F x \text { nom. }}+50 * \frac{\|F z\|}{F z \text { nom. }}+70 * \frac{\sqrt{M x^{2}+M y^{2}}}{M x \text { nom. }}+100 * \frac{\|M z\|}{M z \text { nom. }} \leq 250$ <br> Please note: The sensor's coordinate origin is in the geometric center of the sensor. When calculating the maximum operational force, the additional bending moments due to leverage effects must be taken into account for the acting lateral forces. <br> Example: Force-controlled grinding process with simultaneous dynamic loads of up to: $\begin{gathered} F x=500 \mathrm{~N} / \mathrm{Fy}=500 \mathrm{~N} / \mathrm{Fz}=1.5 \mathrm{kN} / \mathrm{Mx}=20 \mathrm{~N} / \mathrm{My}=20 \mathrm{~N} / \mathrm{Mz}=40 \mathrm{~N} \\ \mathbf{L m a x}=\mathbf{1 0 0} * \frac{\sqrt{\mathbf{5 0 0 N ^ { \mathbf { 2 } } + \mathbf { 5 0 0 \mathbf { N } ^ { 2 } }}} \underset{\mathbf{1 0 0 0}}{ }+\mathbf{5 0} * \frac{\mathbf{1 5 0 0 N}}{\mathbf{2 0 0 0}}+\mathbf{7 0} * \frac{\sqrt{\mathbf{2 0 \mathbf { N m } ^ { 2 } + \mathbf { 2 0 N m }}}}{\mathbf{5 0 N m}}+\mathbf{1 0 0} * \frac{\mathbf{4 0 N m}}{\mathbf{5 0 N m}}=227.80}{} \end{gathered}$ |
| Dynamic performance |  | recommended: 50 \% |
| Material |  | high-strength aluminum |
| Protection class (EN 60529) |  | IP40 |
| Other |  |  |
| Natural frequency |  | $>1800 \mathrm{~Hz}$ |
| Mass | [g] | 800 |

The data in the area $20 \%-100 \%$


## Electrical termination

## Output signal

burster load cells are based on a strain-gage Wheatstone bridge. This measurement principle means that the output voltage $\mathrm{mV} / \mathrm{V}$ is highly dependent on the sensor supply voltage. Our website contains details of suitable instrumentation amplifiers, indicator and display devices and process instruments.


| Connector pin assignment |  |  |  |
| :---: | :---: | :---: | :---: |
| Measurement channel | Assignment |  | Pin |
| Fx | Us+ | Excitation (+) | A |
|  | Us- | Excitation (-) | B |
|  | Um+ | Measurement signal (+) | C |
|  | Um- | Measurement signal (-) | D |
| Fy | Us+ | Excitation (+) | E |
|  | Us- | Excitation (-) | F |
|  | Um+ | Measurement signal (+) | G |
|  | Um- | Measurement signal (-) | H |
| Fz | Us+ | Excitation ( + ) | J |
|  | Us- | Excitation (-) | K |
|  | Um+ | Measurement signal (+) | L |
|  | Um- | Measurement signal $(-)$ | M |
| Mx | Us+ | Excitation ( + ) | N |
|  | Us- | Excitation (-) | P |
|  | Um+ | Measurement signal (+) | R |
|  | Um- | Measurement signal $(-)$ | S |
| My | Us+ | Excitation ( + ) | T |
|  | Us- | Excitation (-) | U |
|  | Um+ | Measurement signal (+) | V |
|  | Um- | Measurement signal (-) | W |
| Mz | Us+ | Excitation (+) | X |
|  | Us- | Excitation (-) | Y |
|  | Um+ | Measurement signal (+) | Z |
|  | Um- | Measurement signal (-) | a |
|  | N.C. |  | b |
|  | N.C. |  | c |

Electrical connection

## Accessories

## Connector, cables and devices

Order code

| Connector |  |
| :---: | :---: |
| 9900-V724 | Connector socket 26 pin (included with device) |
| Cables |  |
| 99724-000A-0090030 | Connecting cable, 3m, 3 x strain gage ( $\mathrm{Fx} / \mathrm{Fy} / \mathrm{Fz}$ ) |
| 99724-000B-0090030 | Connecting cable, $3 \mathrm{~m}, 3 \mathrm{x}$ strain gage ( $\mathrm{Mx} / \mathrm{My} / \mathrm{Mz}$ ) |
| 99724-000F-0090030 | Connecting cable, $3 \mathrm{~m}, 6 \mathrm{x}$ strain gage |
| 99209-724A-0090030 | Connecting cable to USB interface 9206-V3xxxx, 3x force, length 3 m , suitable for drag chains |
| 99209-724B-0090030 | Connecting cable to USB interface 9206-V3xxxx, 3x torque, length 3 m , suitable for drag chains |
| 99209-724F-0090030 | Connecting cable to USB interface 9206-V3xxxx, 3x force / 3 x torque, length 3 m , suitable for drag chains |
| Devices |  |
| 9250-VXXXXXX | Universal instrumentation amplifier |
| 9251-VXXXX | Fieldbus controller for the 9250 instrumentation amplifier series |
| 9236-V... | In-line instrumentation amplifier for strain gage sensors |
| 9206-V. | USB sensor interface for strain gage sensors |

## Order Code

| Measuring range |  |  |  |  | Code |  |  |  |  |  |  |  |  | Measuring range |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Fz |  |  |  | Mz |  |  |  |  | $\begin{aligned} & \mathrm{Fz}=0 \ldots \pm 449.6 \mathrm{lbs} \\ & \mathrm{Fy}=0 \ldots \pm 224.8 \mathrm{lbs} \\ & \mathrm{Fx}=0 \ldots \pm 224.8 \mathrm{lbs} \\ & \mathrm{Mz}=0 \ldots \pm 442.5 \mathrm{lbs} \text { in } \\ & \mathrm{My}=0 \ldots \pm 442.5 \mathrm{lbs} \text { in } \\ & \mathrm{Mx}=0 \ldots \pm 442.5 \mathrm{lbs} \text { in } \end{aligned}$ |  |  |  |
|  | $\begin{aligned} & \mathrm{Fz}= \\ & \mathrm{Fy}= \\ & \mathrm{Fx}= \\ & \mathrm{Mz}= \\ & M y= \\ & M \mathrm{C}= \end{aligned}$ | $\begin{array}{rr}  & \pm \\ \cdot & \pm \\ . & \pm \\ . & \pm 5 \\ . . & \pm 5 \\ . . & \pm 5 \end{array}$ | $\begin{aligned} & \mathrm{kN} \\ & \mathrm{kN} \\ & \mathrm{kN} \\ & \mathrm{~N} \end{aligned}$ $\mathrm{Nm}$ $\mathrm{Nn}$ |  | 6 | 0 | 0 | 2 | 5 | 0 | 5 | 0 |  |  |  |  |  |
| 8 | 5 | 6 | 5 | - |  |  |  |  |  |  |  |  | - |  |  | 0 | 0 |
|  |  |  |  |  |  |  |  |  |  |  |  |  |  | $\vdots$ |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 0 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 1 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 2 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 3 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 4 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 5 |  |  |  |
| - Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 6 |  |  |  |
| ■ Force: Fz / Fy / Fx |  |  |  |  |  |  |  |  |  |  |  |  |  | 7 |  |  |  |
| - Torque: $\mathrm{Az} / \mathrm{My} / \mathrm{Ax}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 0 |  |  |
| - Torque: $\mathrm{Az} / \mathrm{Ay} / \mathrm{Mx}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 1 |  |  |
| Torque: Azz / My / Mx |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 2 |  |  |
| - Torque: Az / M M / Mx |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 3 |  |  |
| - Torque: Mz / $\mathrm{Aly}_{\text {/ }}$ / $\mathrm{A}^{*}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 4 |  |  |
| Torque: Mz / Ay / Mx |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 5 |  |  |
| - Torque: Mz / My / A $\mathbf{A}^{\text {\% }}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 6 |  |  |
| Torque: Mz / My / Mx |  |  |  |  |  |  |  |  |  |  |  |  |  |  | 7 |  |  |

## Example order

| Ordering example |  |  |
| :--- | :--- | :--- |
| 1 x | Sensor with application 3 x force $/ 3 \mathrm{x}$ torque | Type 8565-6002-5050-7700 |
| 1 x | Connecting cable, open cable end, length 3 m , suitable for drag chains | Type 99209-724F-0090030 |
| 6 x | Single-channel in-line instrumentation amplifier for strain gage sensors | Type 9236-V000 |
| 6 C | Calibrate a measuring chain | 92ABG |

## Note

## Brochure

Our brochure "Load cells - for production automation, R\&D and quality assurance" is available for download on our website or can be requested. It contains numerous applications, detailed product specifications and overviews.

## Product videos

You can find our installation videos at: www.youtube.com/bursterVideo

- CAD datc

Download via www.burster.de or directly from www.traceparts.de


YouTube

